

A Language and Smoothed Semantics for Convergent Stochastic Gradient Descent

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$$\operatorname{argmin}_{\theta} \mathbb{E}_{z \sim q} [f(\theta, z)]$$

no dependence on θ

expressed in PL with conditionals,
may *not* be *differentiable/continuous*

Example: maximisation of ELBO for reparametrised models in *variational inference*

$$\text{ELBO}(\theta) := \mathbb{E}_{z \sim q} [\log p(\phi_{\theta}(z)) - \log q_{\theta}(\phi_{\theta}(z))]$$

$$\operatorname{argmin}_{\theta} \mathbb{E}_{z \sim q} [f(\theta, z)]$$

no dependence on θ

expressed in PL with conditionals,
may *not* be *differentiable/continuous*

Aim: find *stationary* point, i.e. θ s.t. $\nabla_{\theta} \mathbb{E}_{z \sim q} [f(\theta, z)] = 0$

Stochastic Gradient Descent (SGD)

$$\theta_{k+1} = \theta_k - \alpha_k \cdot \underbrace{\nabla_{\theta} f(\theta_k, z_k)}_{\text{reparametrisation gradient estimator}}$$

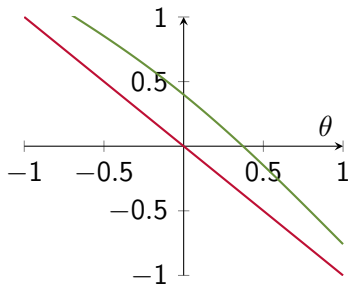
$$z_k \sim q$$

*Reparametrisation gradient estimator
for non-differentiable models is **biased!***

[Lee et al., NeurIPS 2018]

$$f(\theta, z) = -0.5 \cdot \theta^2 + \begin{cases} 0 & \text{if } z + \theta < 0 \\ 1 & \text{otherwise} \end{cases}$$

$$\mathbb{E}_{\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{1})} [\nabla_{\theta} f(\theta, \mathbf{z})] = -\theta \neq -\theta + \mathcal{N}(-\theta \mid 0, 1) = \nabla_{\theta} \mathbb{E}_{\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{1})} [f(\theta, \mathbf{z})]$$



*Vanishing gradient estimator does **not imply stationarity!***

Contributions

Provable convergence to stationary points (and unbiased gradient estimators) for *typable* programs.

Approach:

- ▶ *Smoothen* (discontinuous) function using sigmoid with accuracy coefficient
- ▶ Optimise expectation, enhancing accuracy in each step

This talk:


- *Reparametrisation* programming language
- Type system and smoothed semantics
- *Convergence* of *Diagonalisation* Stochastic Gradient Descent, a new variant of SGD

Reparametrisation Programming Language

simply typed λ -calculus with \mathbb{R} , $+$, \cdot and *conditionals*

+ *sampling* from standard normal
transformed by *diffeomorphic* polynomials

$M ::= \dots$
| **if** $M < 0$ **then** M **else** M
| $\phi_{\theta}(M, \dots, M, \text{sample})$



diffeomorphic polynomial

Example: sample from $\mathcal{N}(\mu, \sigma)$ using $\phi_{\mu, \sigma}(\text{sample})$, where $\phi_{\mu, \sigma}(z) := \sigma \cdot z + \mu$

$$\operatorname{argmin}_{\theta} \mathbb{E}_{\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} [\mathbf{f}_{\mathbf{M}}(\theta, \mathbf{z})]$$

where f_M is the *value*-function of a term $M : R$ with parameters $\theta : R$.


(Integrability) $\mathbb{E}_{\mathbf{z} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})} [|f_M(\theta, \mathbf{z})|] < \infty$ for all $\theta \in \mathbb{R}^n$.

Type System

ensure *guards do not directly depend on parameters*
(only after transformation)

if $\theta < 0$ then 0 else 1 

$(\lambda x. \text{if } x < 0 \text{ then } 0 \text{ else } 1) \theta$ 

$(\lambda x. \text{if } x < 0 \text{ then } 0 \text{ else } 1) (\phi_{\theta}(\text{sample}))$ 

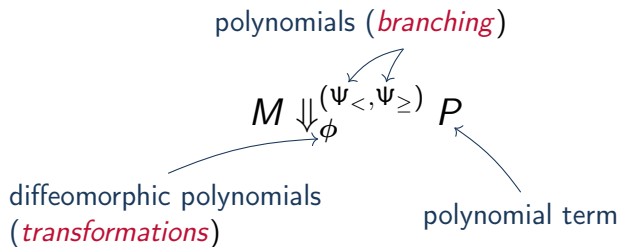
$(\lambda x. \underline{-0.5} \cdot \theta^2 + (\text{if } x < 0 \text{ then } \underline{0} \text{ else } \underline{1})) (\phi_{\theta}(\text{sample}))$ 

Reparametrisation-aware symbolic execution

variant of [Mak et al., ESOP 2021]

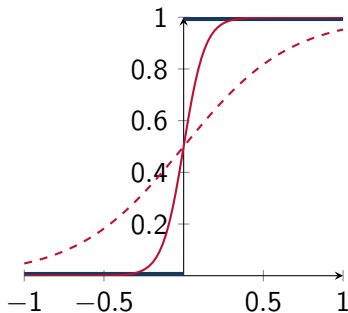
- ▶ Collect constraints due to *branching*
- ▶ Replace $\phi_{\theta}(P_1, \dots, P_{\ell}, \mathbf{sample})$ with fresh sampling variable α_j and keep track of *transformations*

$$\emptyset \mid \emptyset \vdash_{\theta} M : R$$



“Standard” Semantics for accuracy coefficient $k \in \mathbb{N}$

$$f_M(\theta, z) = \sum_{M \Downarrow_{\phi}^{(\Psi_{<}, \Psi_{\geq})} P} f_P(\theta, \phi_{\theta}(z)) \cdot \prod_{\psi \in \Psi_{<}} [\psi(\phi_{\theta}(z)) < 0] \cdot \prod_{\psi \in \Psi_{\geq}} [\psi(\phi_{\theta}(z)) \geq 0]$$



Smoothed Semantics for accuracy coefficient $k \in \mathbb{N}$

$$f_{M,k}(\theta, z) = \sum_{M \downarrow_{\phi}^{(\Psi_{<}, \Psi_{\geq})} P} f_P(\theta, \phi_{\theta}(z)) \cdot \prod_{\psi \in \Psi_{<}} \sigma_{\mathbf{k}}(-\psi(\phi_{\theta}(z))) \cdot \prod_{\psi \in \Psi_{\geq}} \sigma_{\mathbf{k}}(\psi(\phi_{\theta}(z)))$$

*Adapt (backward mode) automatic differentiation
to compute smoothing*

(Unbiasedness) $\nabla_{\mathbf{z}} \mathbb{E}_{\mathbf{z}}[f_{M,k}(\boldsymbol{\theta}, \mathbf{z})] = \mathbb{E}_{\mathbf{z}}[\nabla_{\mathbf{z}} f_{M,k}(\boldsymbol{\theta}, \mathbf{z})]$ for all $k \in \mathbb{N}$.

Use SGD for $f_{M,k}$ for *fixed* $k \in \mathbb{N}$

(Uniform Convergence of Gradients) If $\Theta \subseteq \mathbb{R}^n$ is compact then

$$\nabla_{\mathbf{z}} \mathbb{E}_{\mathbf{z}}[\mathbf{f}_{M,k}(\boldsymbol{\theta}, \mathbf{z})] \xrightarrow{\text{unif}} \nabla_{\mathbf{z}} \mathbb{E}_{\mathbf{z}}[\mathbf{f}_M(\boldsymbol{\theta}, \mathbf{z})] \quad \text{as } k \rightarrow \infty \text{ for } \boldsymbol{\theta} \in \Theta$$

Key trick:

$$\frac{\partial(\sigma_k \circ \psi \circ \phi.)}{\partial \theta_i}(\boldsymbol{\theta}, \mathbf{z}) = \nabla_{\mathbf{z}}(\sigma_k \circ \psi \circ \phi.)(\boldsymbol{\theta}, \mathbf{z}) \cdot \mathbf{J}_{\mathbf{z}}^{-1} \phi_{\boldsymbol{\theta}}(\mathbf{z}) \cdot \mathbf{J}_{\theta_i} \phi_{\boldsymbol{\theta}}(\mathbf{z})$$

(enables integration by parts of $\mathbb{E}_{\mathbf{z}}[\frac{\partial f_{M,k}}{\partial \theta_i}]$)

Diagonalisation Stochastic Gradient Descent (DSGD)

$$\theta_{k+1} = \theta_k - \alpha_k \cdot \nabla_{\theta} \mathbf{f}_{\mathbf{M},k}(\theta_k, \mathbf{z}_k) \qquad \mathbf{z}_k \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

As a consequence of unbiasedness, uniform convergence (of gradients), etc.

Convergence on Typable Programs

If $\emptyset \mid \emptyset \vdash_{\theta} M : R$ then a DSGD sequence $(\theta_k)_{k \in \mathbb{N}}$

1. is unbounded or
2. has a *stationary* accumulation point.

Related Work

[Lee et al., NeurIPS 2018]:

- Fix (biased) reparametrisation gradient estimator for non-differentiable models by additional non-trivial *boundary* terms
- ✗ Only discuss efficient method for *affine* guards
- ✗ Not concerned with *convergence* of SGD
- ✗ No discussion of PL aspects

Conclusion

This work:

- ✓ Type system enforcing very mild restrictions on PL
- ✓ Smoothed semantics avoids boundary term
- ✓ Not only unbiasedness but also *convergence* of DSGD
 - *Asymptotic* result, for each fixed accuracy smoothing (only) approximation

Ongoing and future work:

- Experimental evaluation
- Recursion, beyond polynomials

Conclusion

*Provable convergence to stationary points
(and unbiased gradient estimators)
for typable programs.*

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